

3D Visibility Representations of 1-planar Graphs

Patrizio Angelini¹, Michael A. Bekos¹,
Michael Kaufmann¹, and Fabrizio Montecchiani²

¹University of Tübingen, Germany

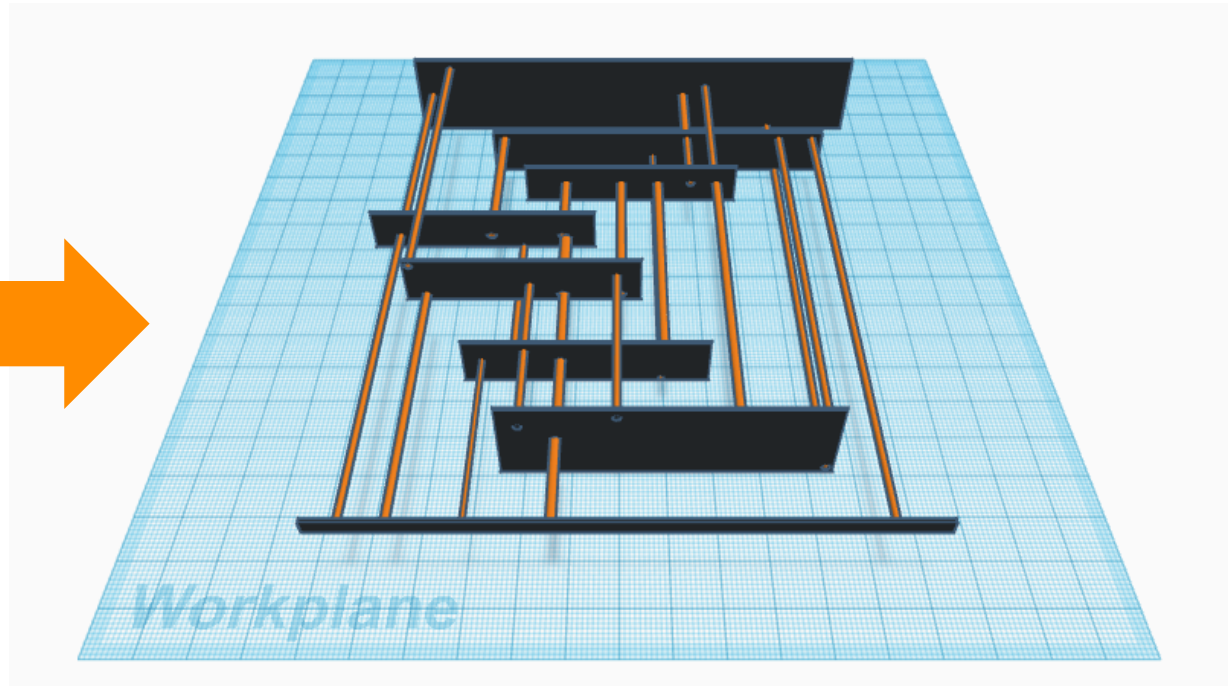
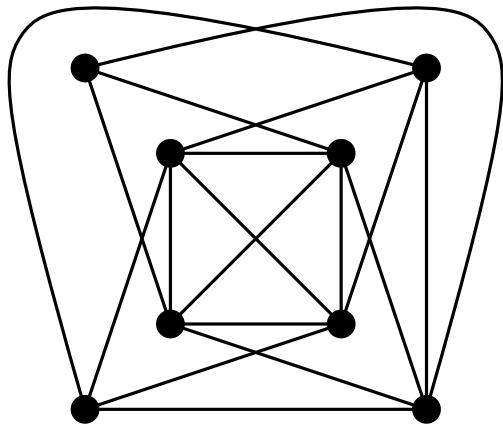
²University of Perugia, Italy

GD 2017, September 25-27, 2017, Boston

Workplane

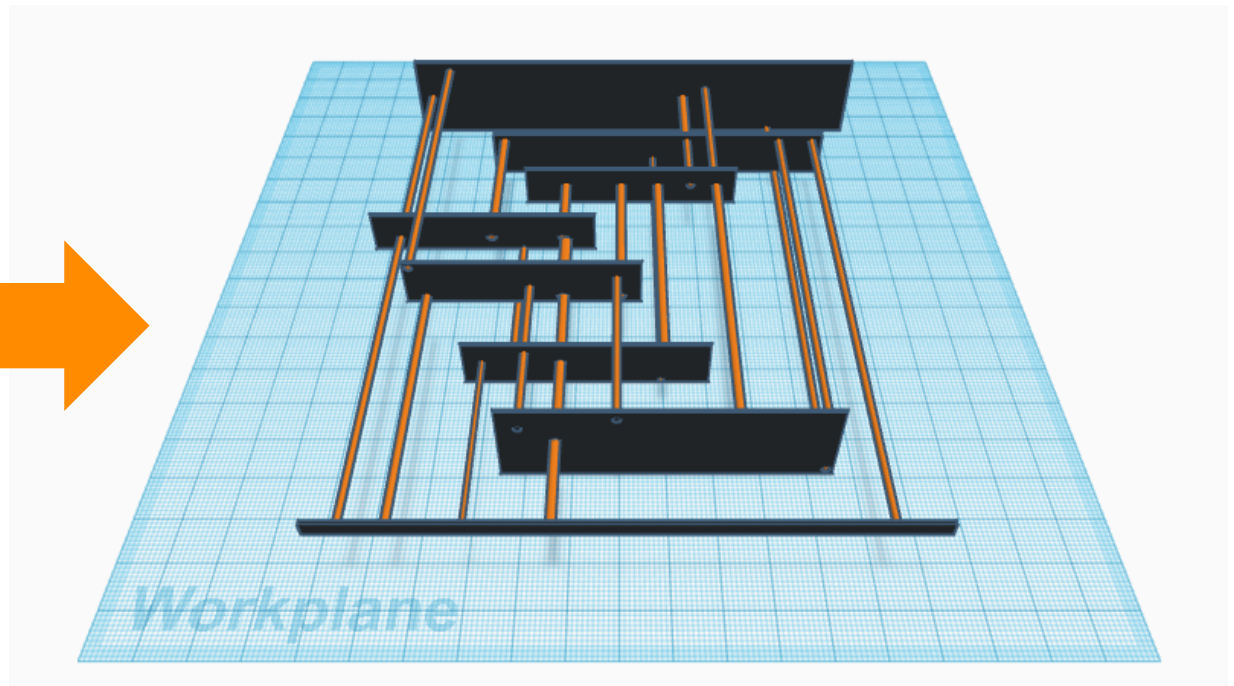
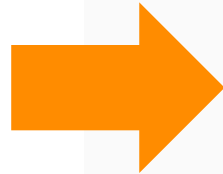
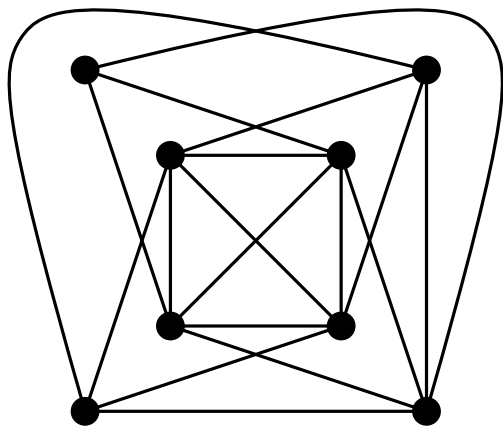
In this presentation...

We will show that every 1-planar graph can be realized as a visibility representation of parallel rectangles in 3D



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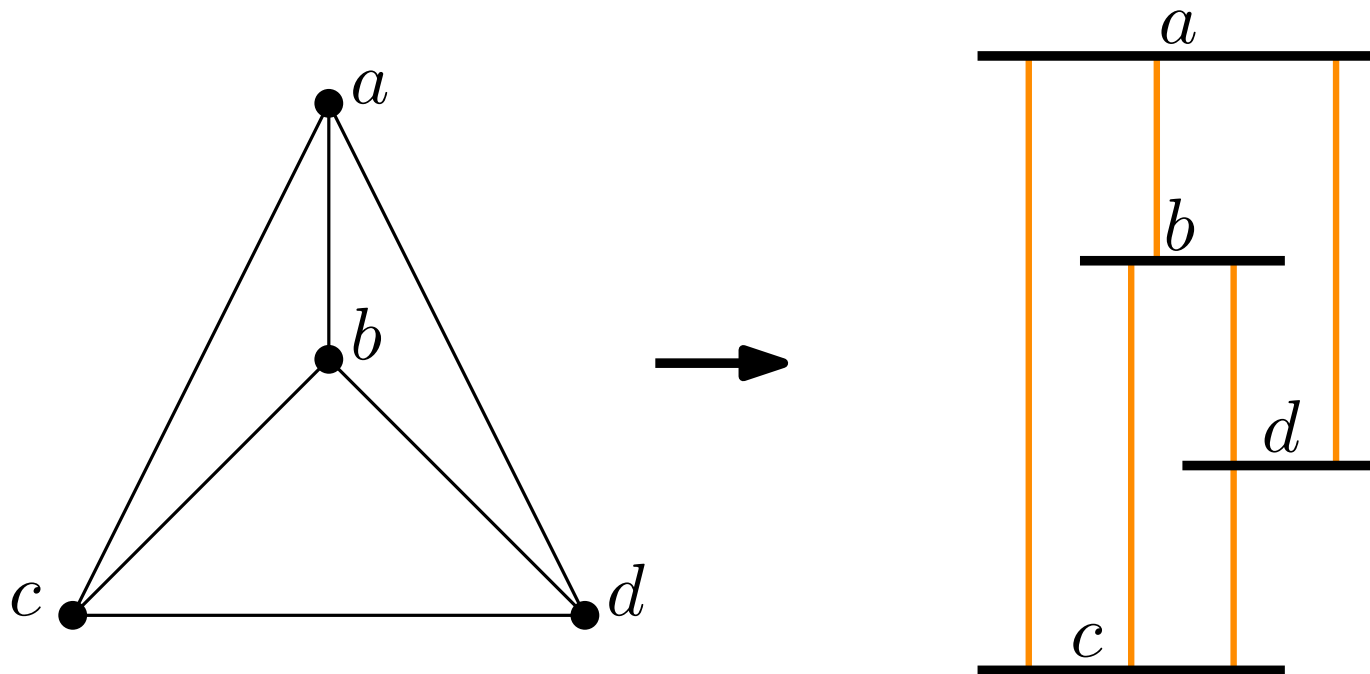


2D Planar Visibility Representations

Bar Visibility Representation (BVR) of a planar graph G :

Vertices \rightarrow Horizontal bars

Edges \rightarrow Vertical unobstructed visibilities



Every planar graph admits a (weak) BVR

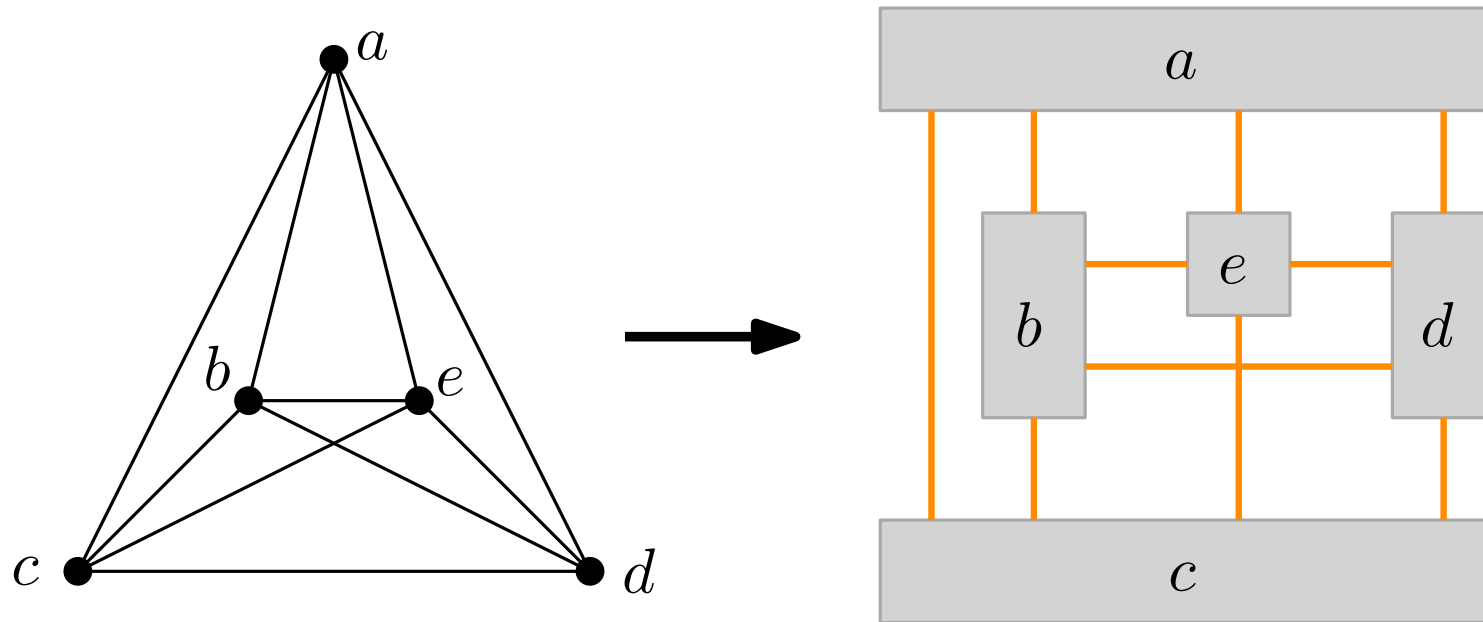
[Duchet et al. 1983, Thomassen 1984, Wismath 1985,
Rosenthal & Tarjan 1986, Tamassia & Tollis 1986]

2D Nonplanar Visibility Representations

Rectangle Visibility Representation (RVR) of a graph G :

Vertices \rightarrow Axis-aligned rectangles

Edges \rightarrow Horizontal/Vertical unobstructed visibilities



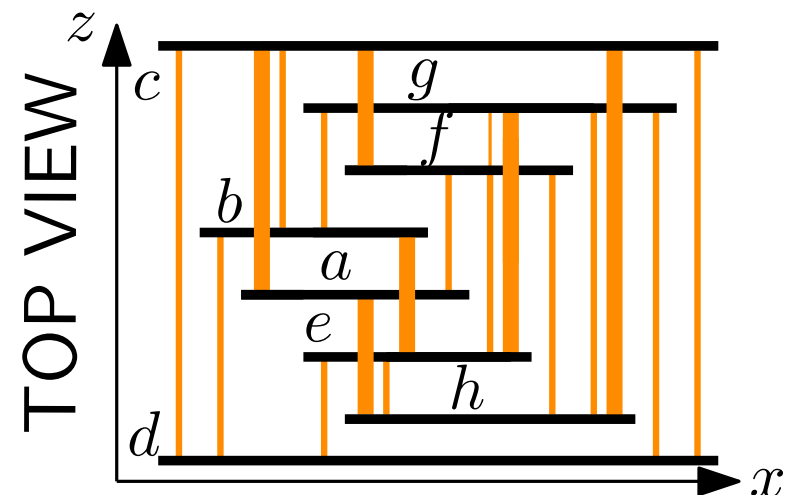
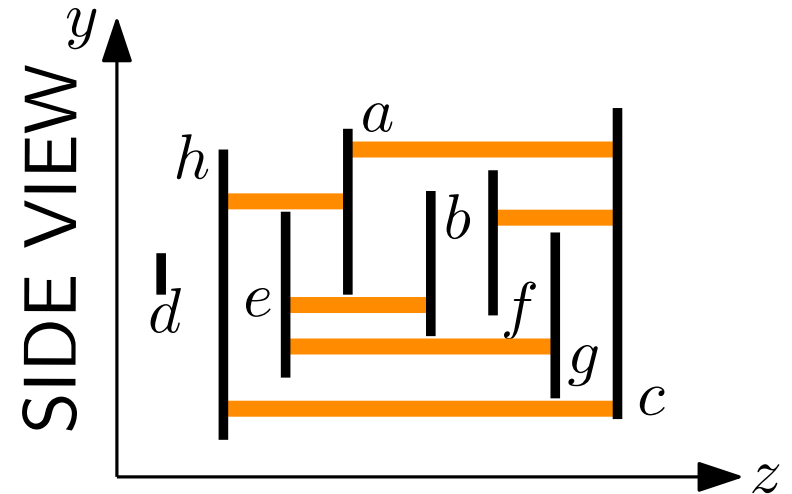
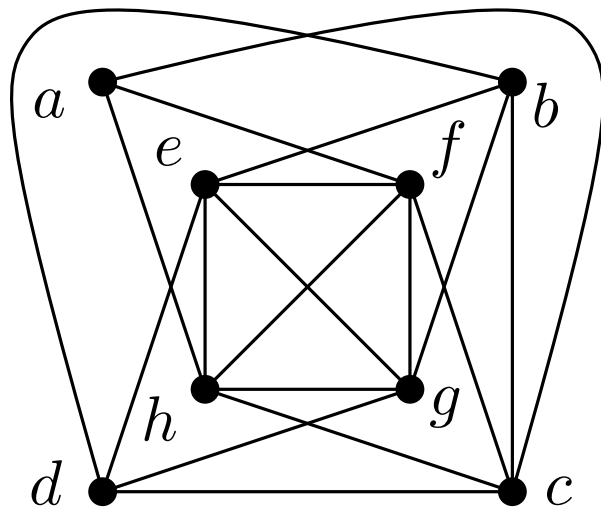
An n -vertex graph that admits an RVR has thickness at most two and at most $6n - 20$ edges [Hutchinson et al. 1999]

3D Visibility Representations

z -parallel Visibility Representation (ZPR) of a graph G :

Vertices \rightarrow Rectangles with sides parallel to x - and y -axis

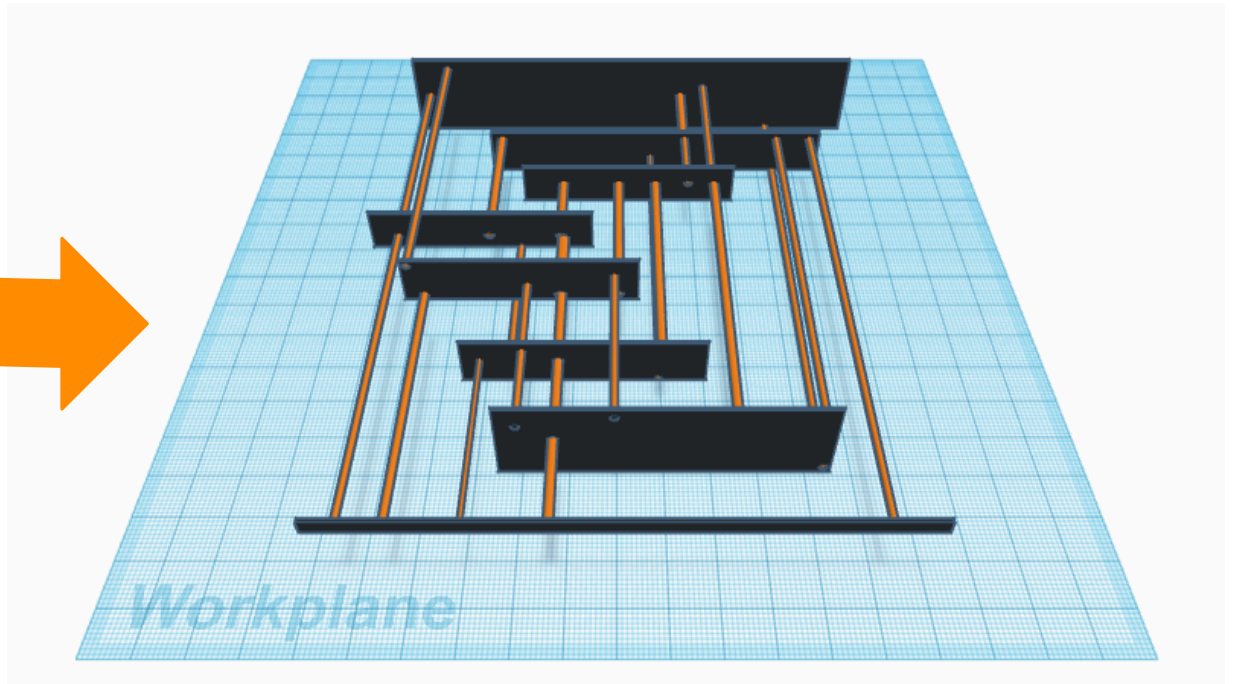
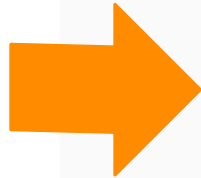
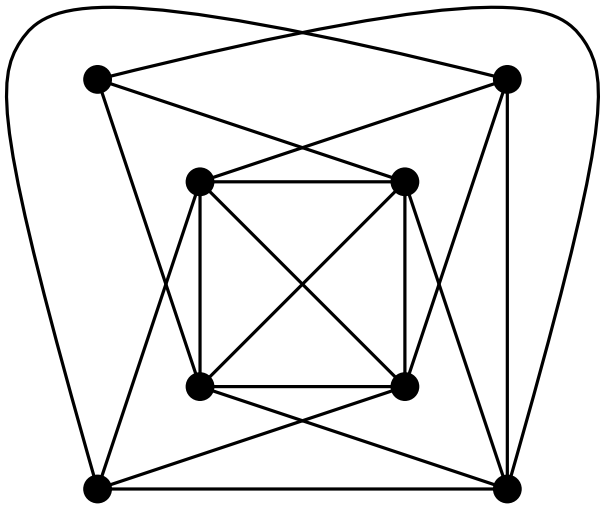
Edges \rightarrow Unobstructed visibilities parallel to z -axis



K_{22} admits a ZPR [Bose et al. 1998]
while K_{51} does not admit any
ZPR [Štola 2009]

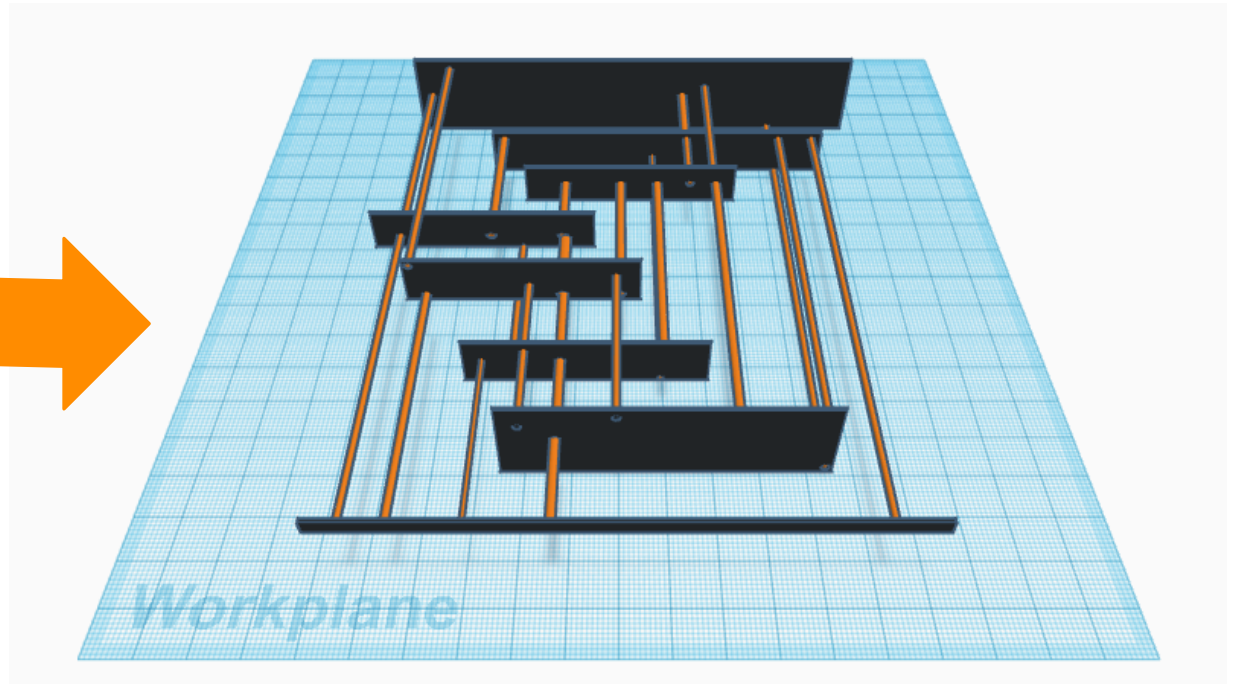
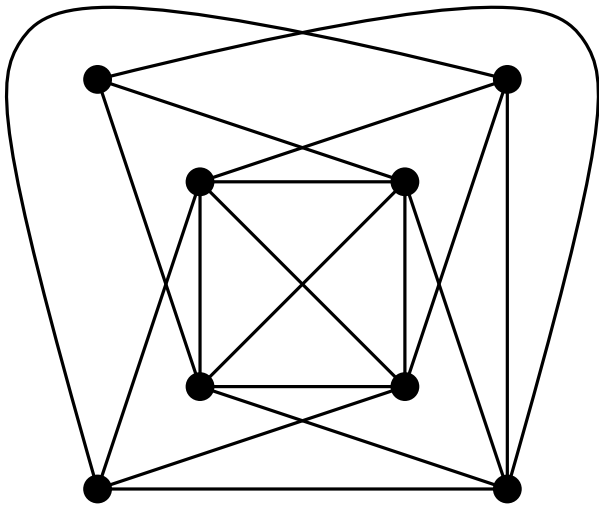
In this presentation...

We will show that every 1-planar graph can be realized as a **z -parallel visibility representation**



In this presentation...

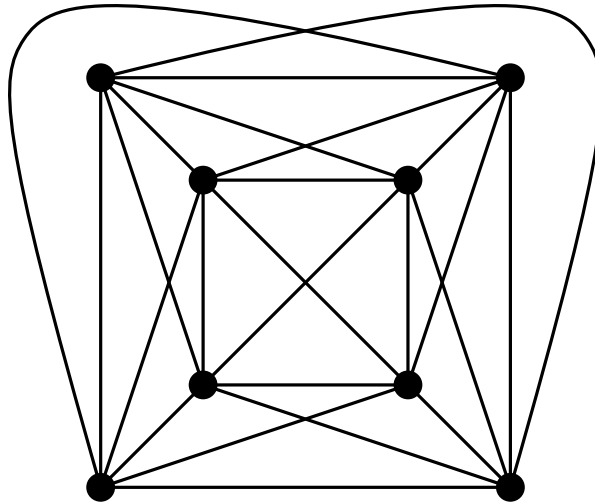
We will show that every **1-planar graph** can be realized as a z -parallel visibility representation



1-planar Graphs

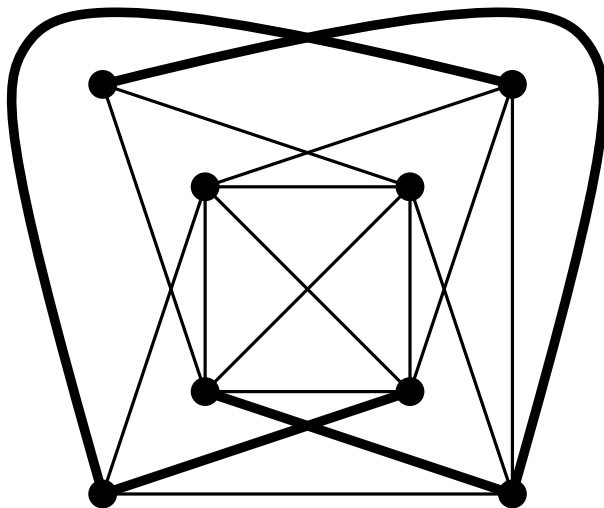
A graph is **1-planar** if it can be drawn with at most one crossing per edge

A 1-planar graph has at most $4n - 8$ edges (tight) [Bodendiek et al. 1983; Pach and Tóth 1997]



1-planar Graphs and Visibility Representations

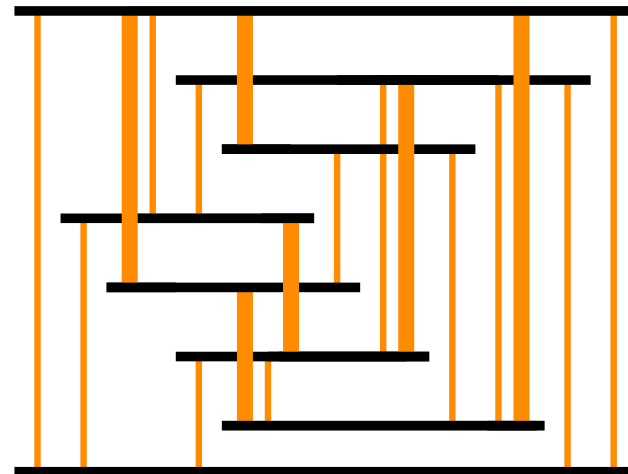
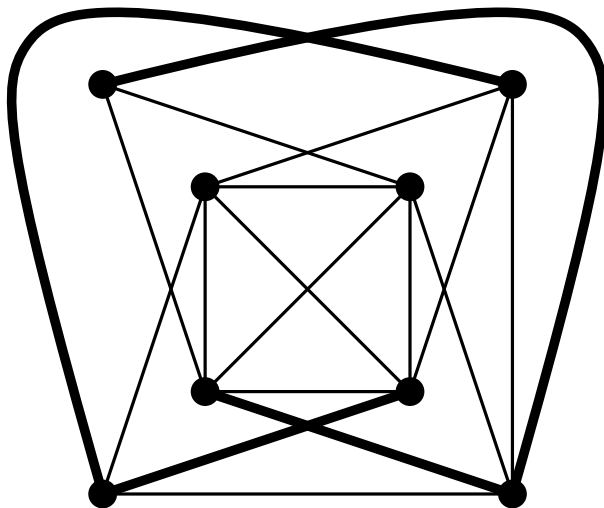
There are 1-planar graphs that do not admit any rectangle visibility representation [Biedl, Liotta, M. 2016]



1-planar Graphs and Visibility Representations

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Every 1-planar graph admits a bar 1-visibility representation [Brandenburg 2014 & Evans et al. 2014]

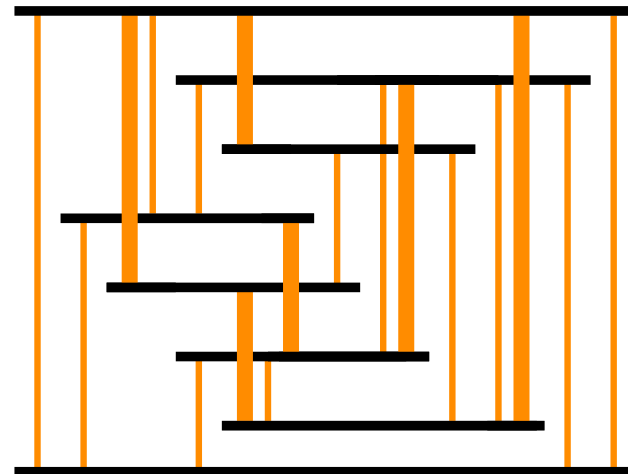
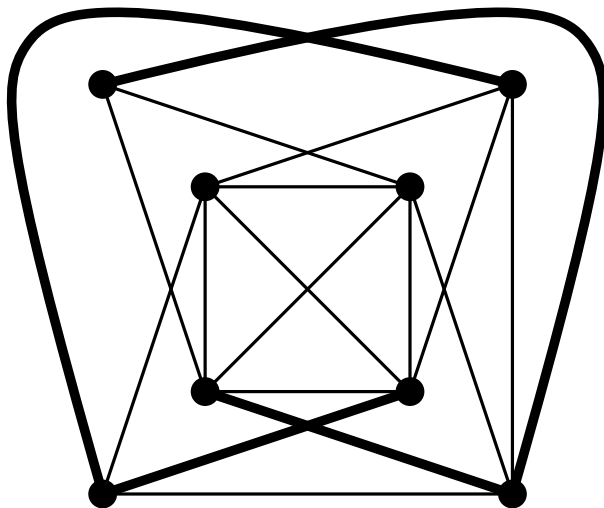


1-planar Graphs and Visibility Representations

There are 1-planar graphs that do not admit any rectangle visibility representation [Biedl, Liotta, M. 2016]

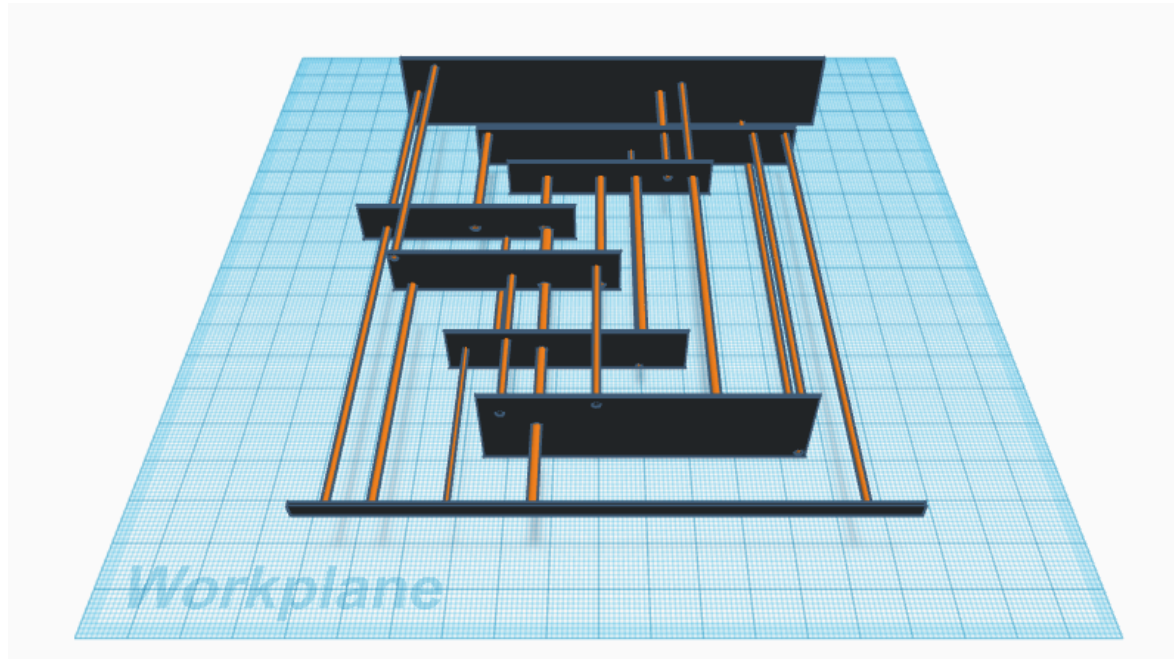
Every 1-planar graph admits a bar 1-visibility representation [Brandenburg 2014 & Evans et al. 2014]

Question: Can we realize every 1-planar graph as a visibility representation of rectangles with unobstructed visibilities by exploiting the 3rd dimension?



In this presentation...

Theorem 1 *Every 1-planar graph G with n vertices admits a ZPR γ in $O(n^3)$ volume. Also, if a 1-planar embedding of G is given as part of the input, then γ can be computed in $O(n)$ time.*

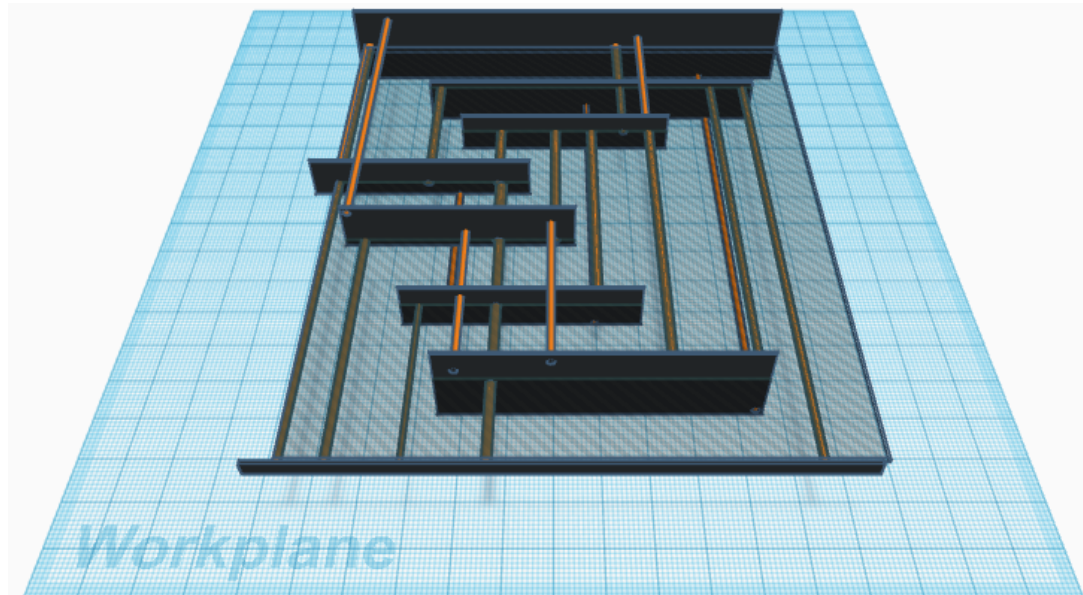


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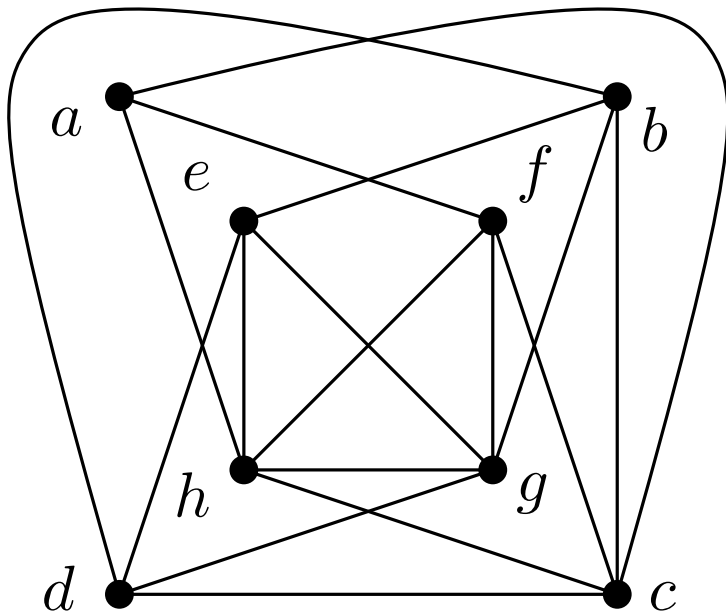
The ZPR γ is **1-visible**:

\exists a plane orthogonal to the rectangles of γ and whose intersection with γ is a B1VR



Proof overview

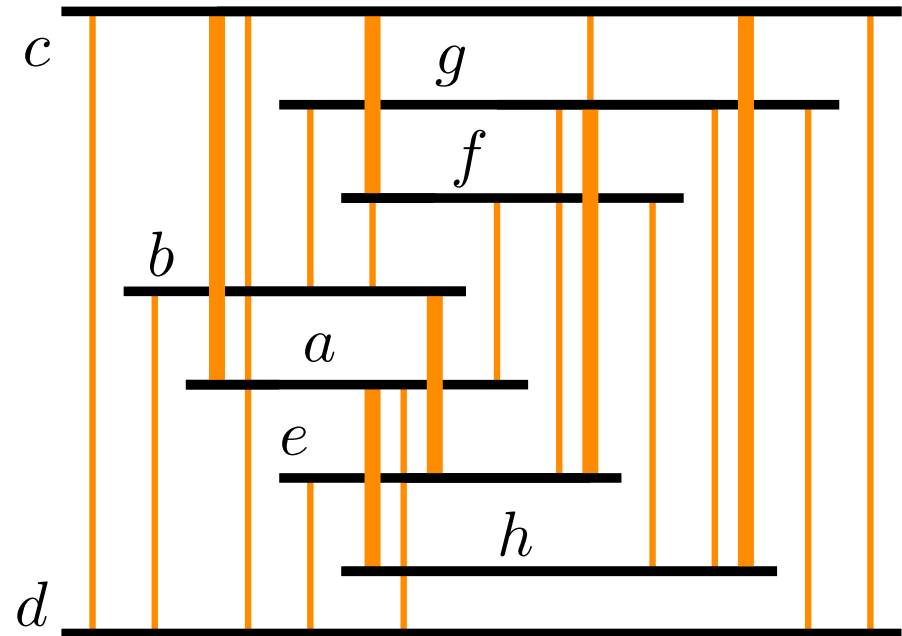
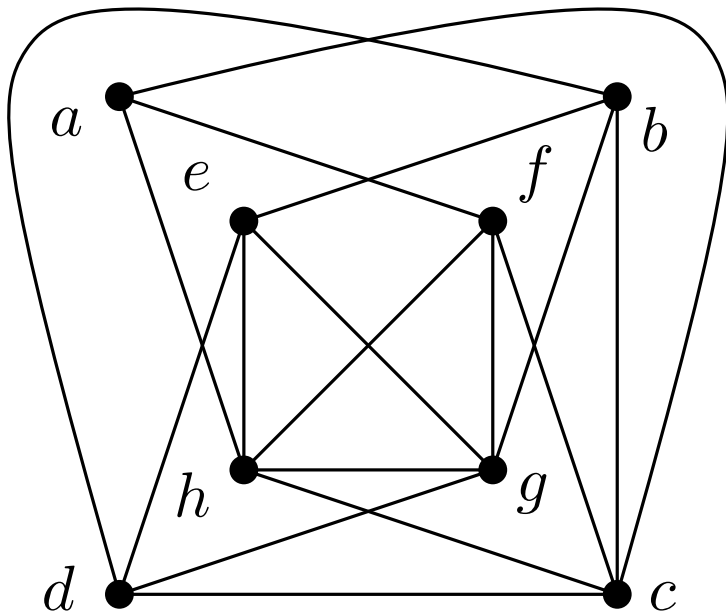
Input: 1-plane graph G



Proof overview

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Step 1: Compute a B1VR γ_1

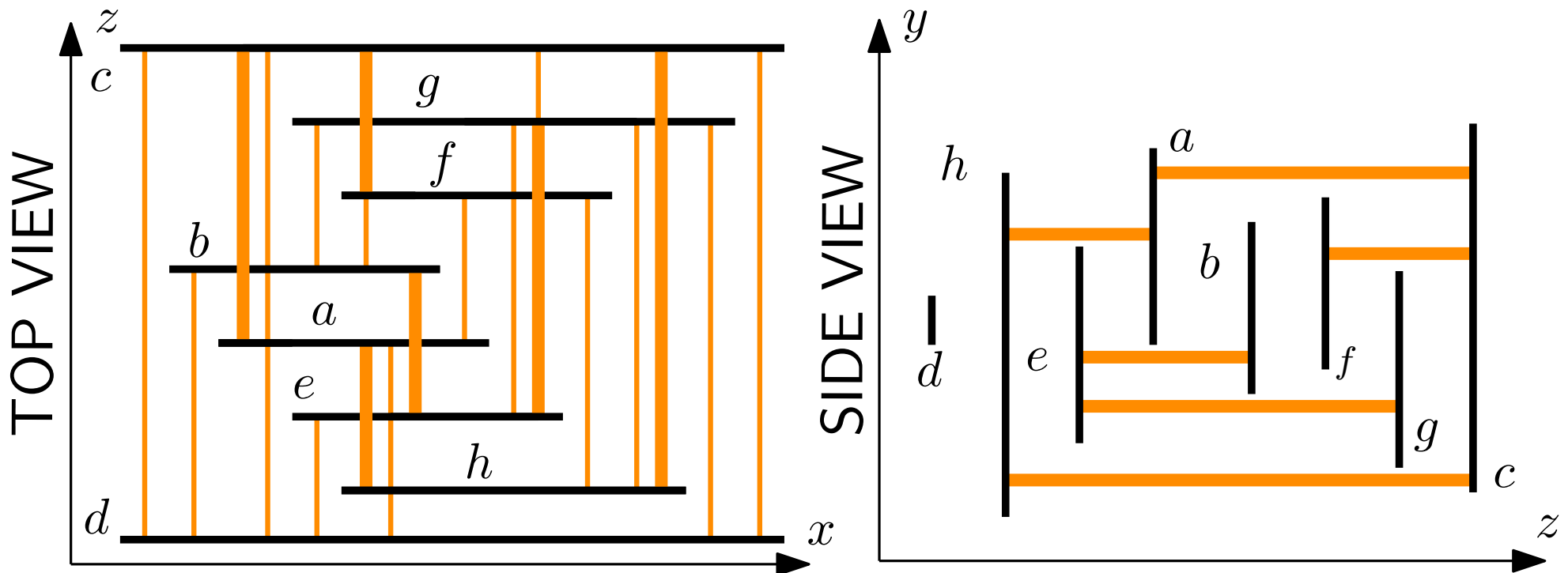


Proof overview

Input: 1-plane graph G

Step 1: Compute a B1VR γ_1

Step 2: Transform every bar into a rectangle by computing the y -coordinates of top and bottom sides, s.t. each visibility that traverses a bar in γ_1 can be moved upward or downward so to avoid the obstacle



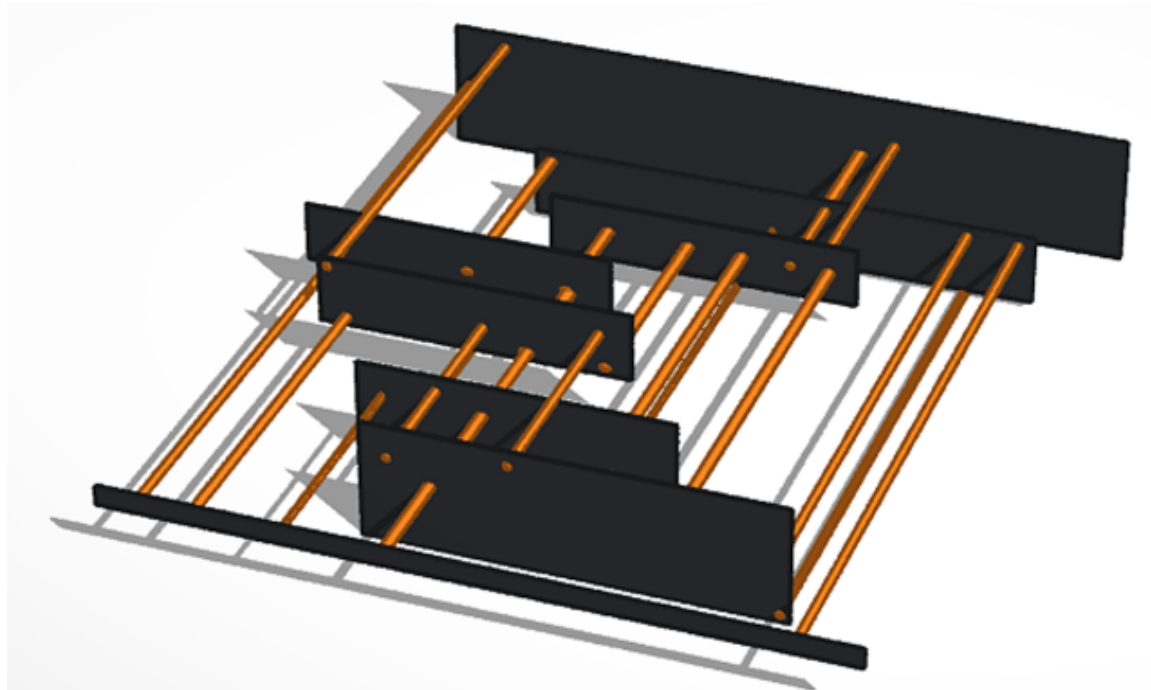
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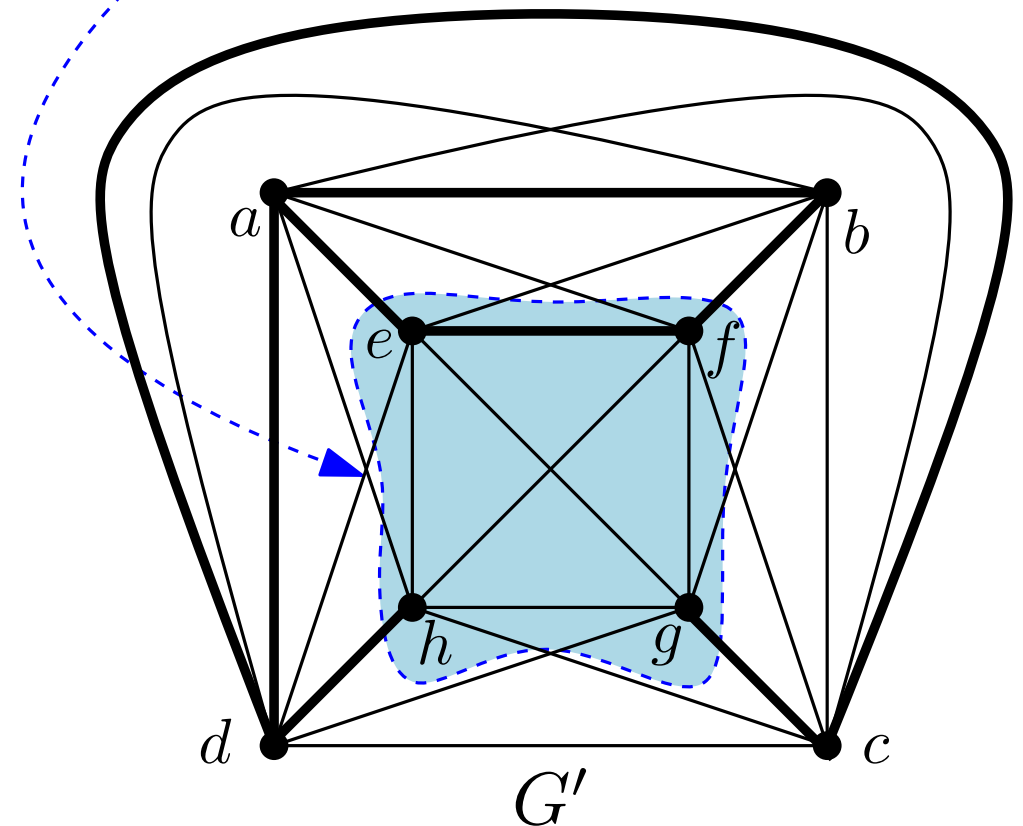
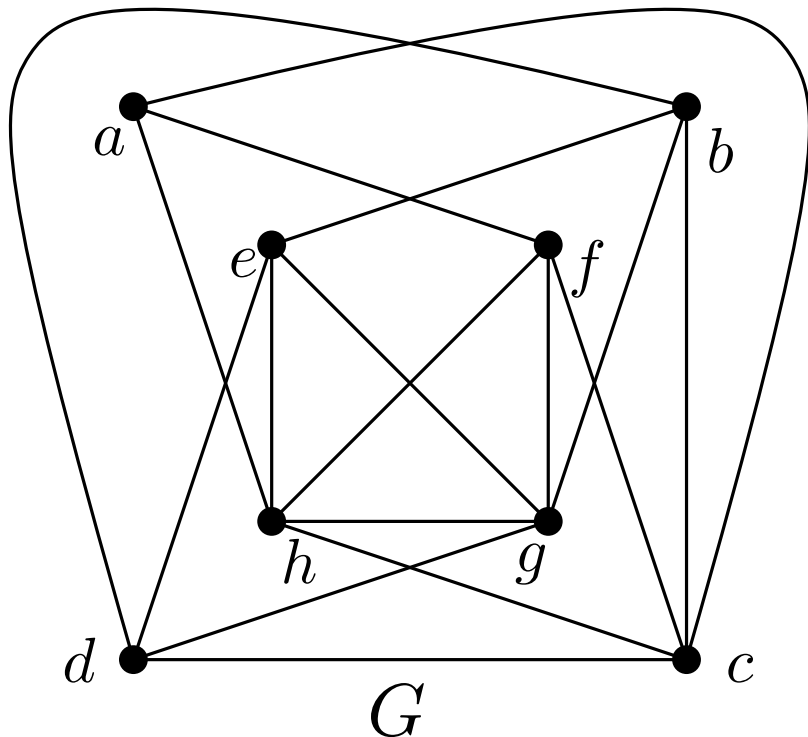
Output: 1-visible ZPR γ of G



Step 1: B1VR

Step 1: We compute a B1VR γ_1 of G by applying Brandenburg's linear-time algorithm [Brandenburg 2014]

1.a A 1-plane multigraph $G' = (V, E' \supseteq E)$ is computed from G such that the four end-vertices of each pair of crossing edges of G' induce a kite

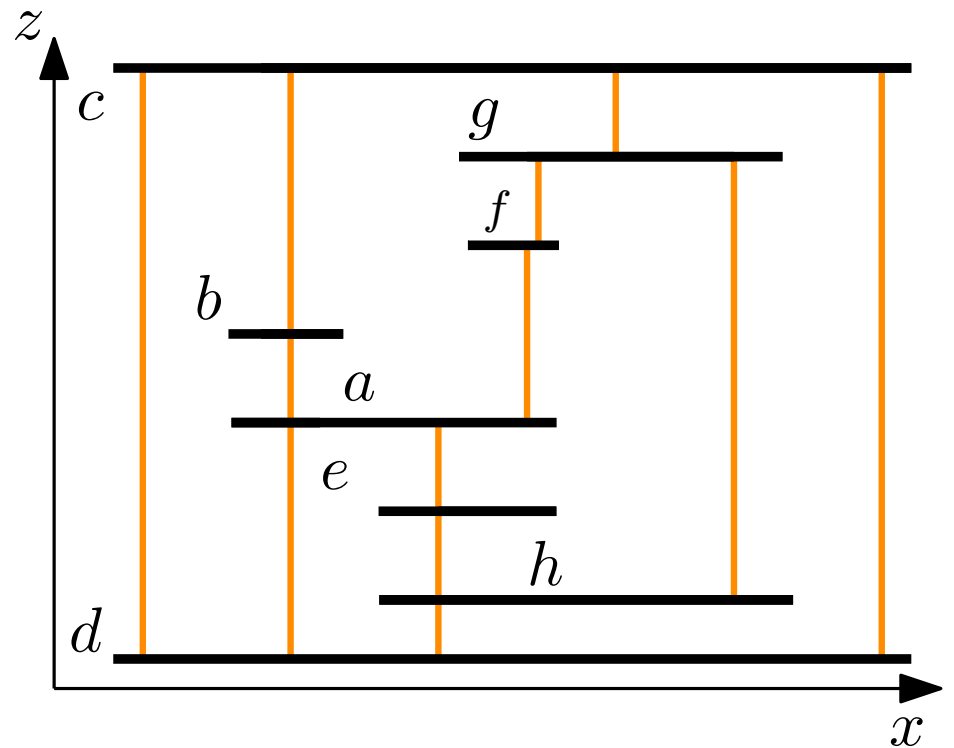
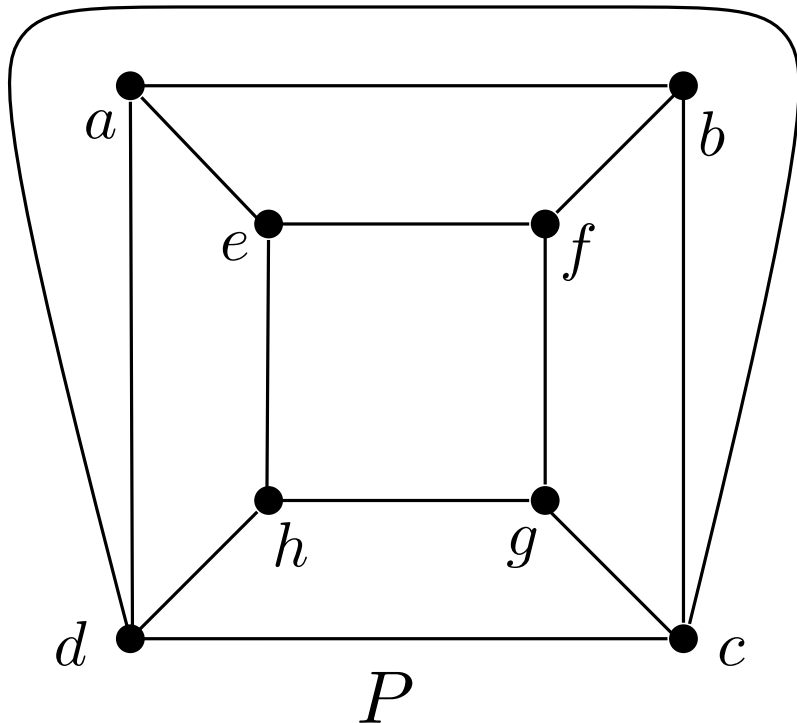


Step 1: B1VR

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1.b Remove all pairs of crossing edges from G' and obtain a planar (multi)graph P

Apply the algorithm by Tamassia and Tollis [Tamassia-Tollis 1986] to compute a BVR of P

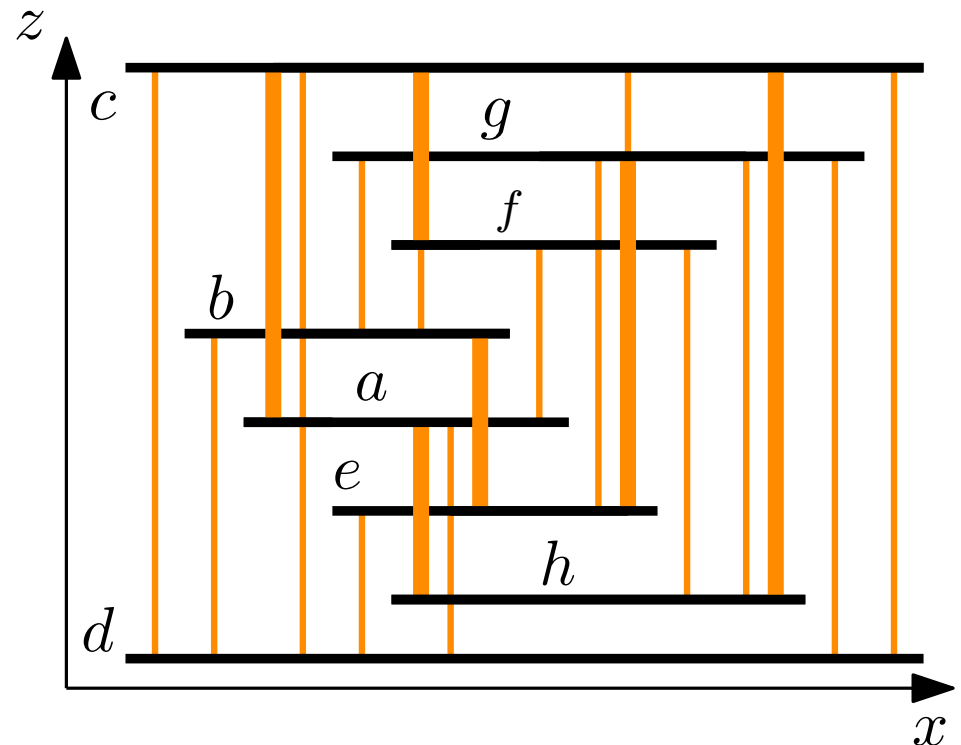
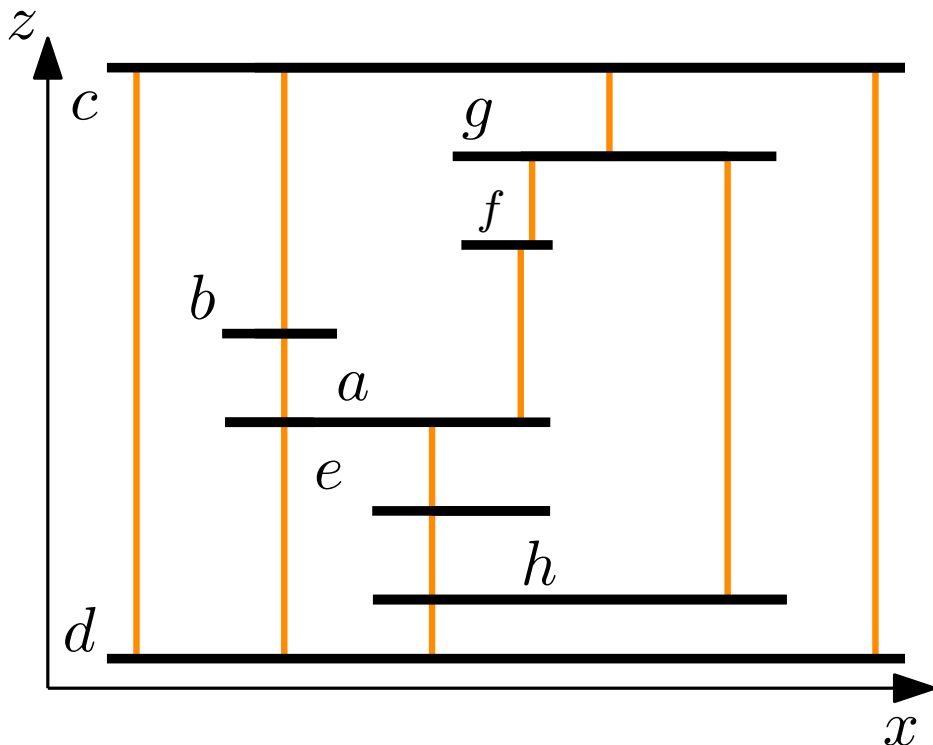


Step 1: B1VR

Step 1: We compute a B1VR γ_1 of G by applying Brandenburg's linear-time algorithm [Brandenburg 2014]

1.c Reinsert all pairs of crossing edges by extending some bars so to introduce new visibilities

The introduced visibilities traverse at most one bar each

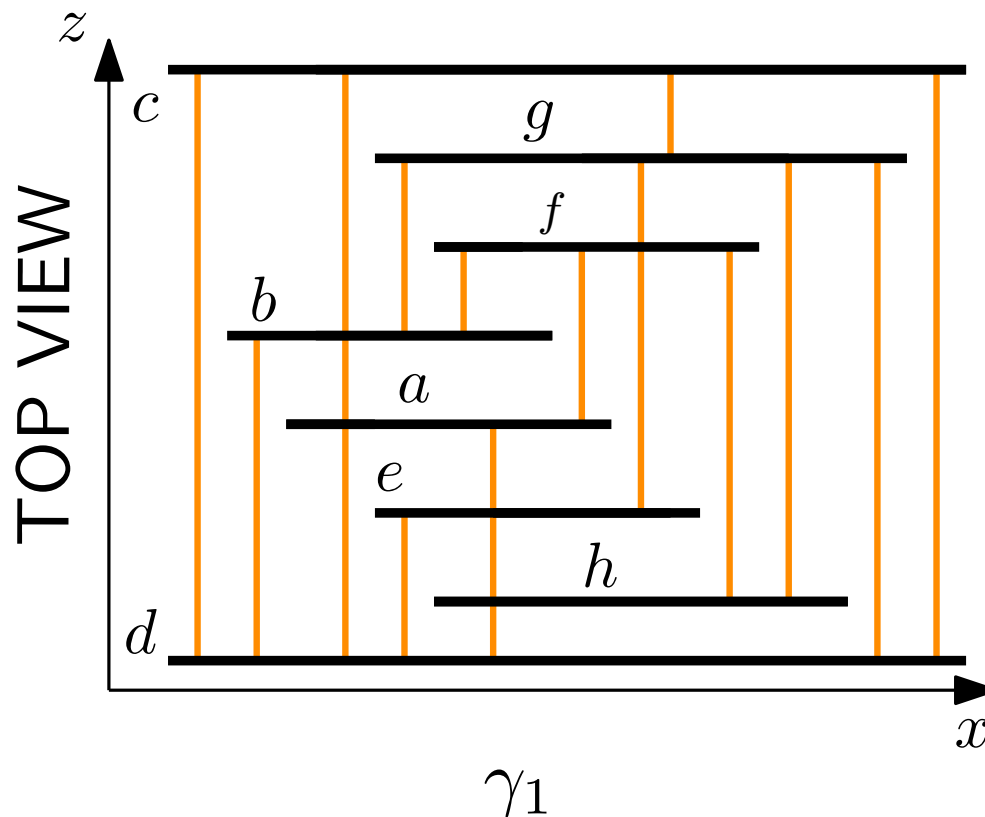


γ_1 Area: $O(n) \times O(n)$

Step 2: 1-visible ZPR

Step 2: Transform the B1VR γ_1 into the ZPR γ

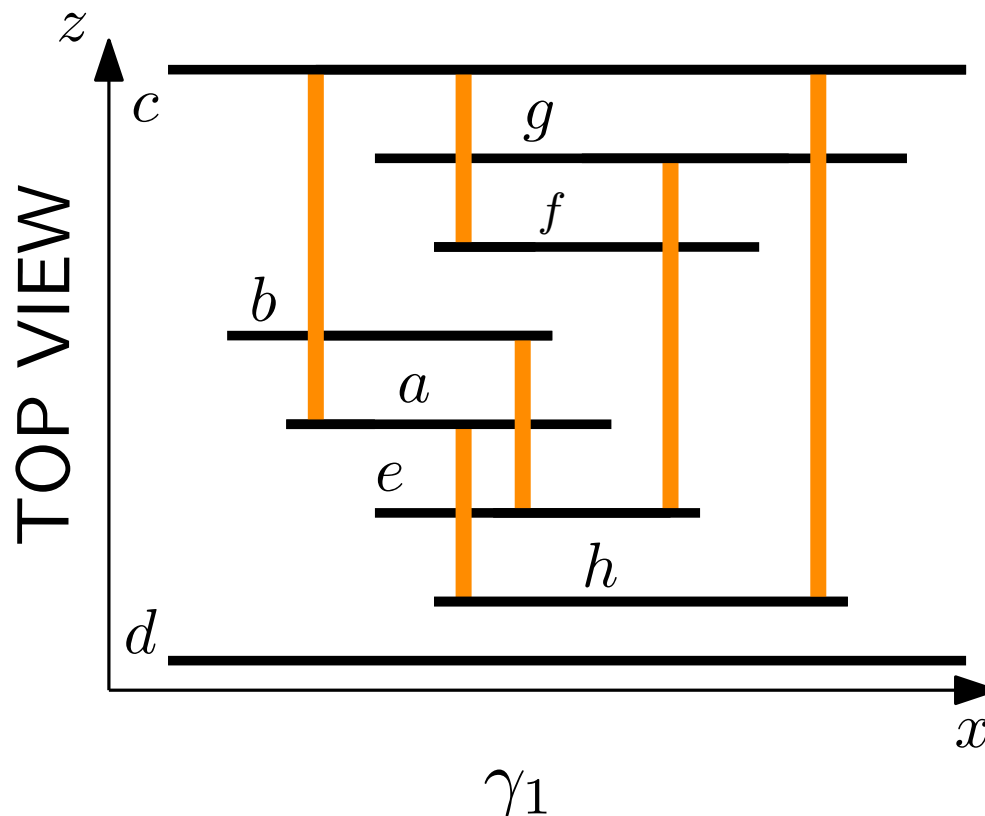
Note: All the visibilities of γ_1 that do not traverse any bar does not need to be moved



Step 2: 1-visible ZPR

Step 2: Transform the B1VR γ_1 into the ZPR γ

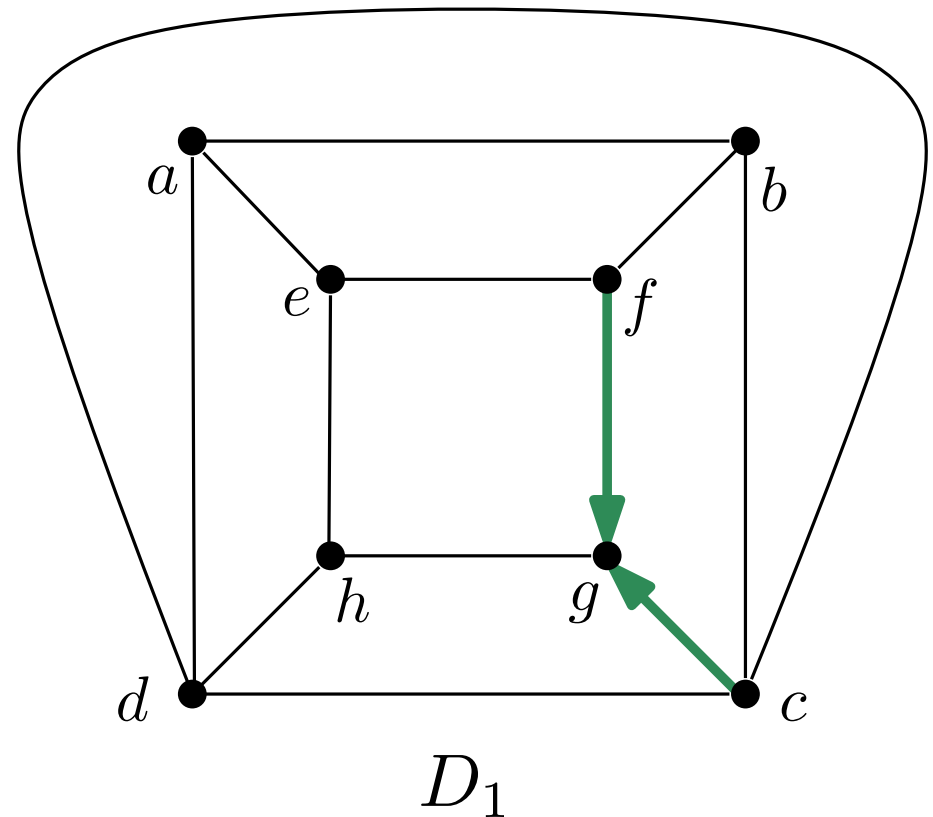
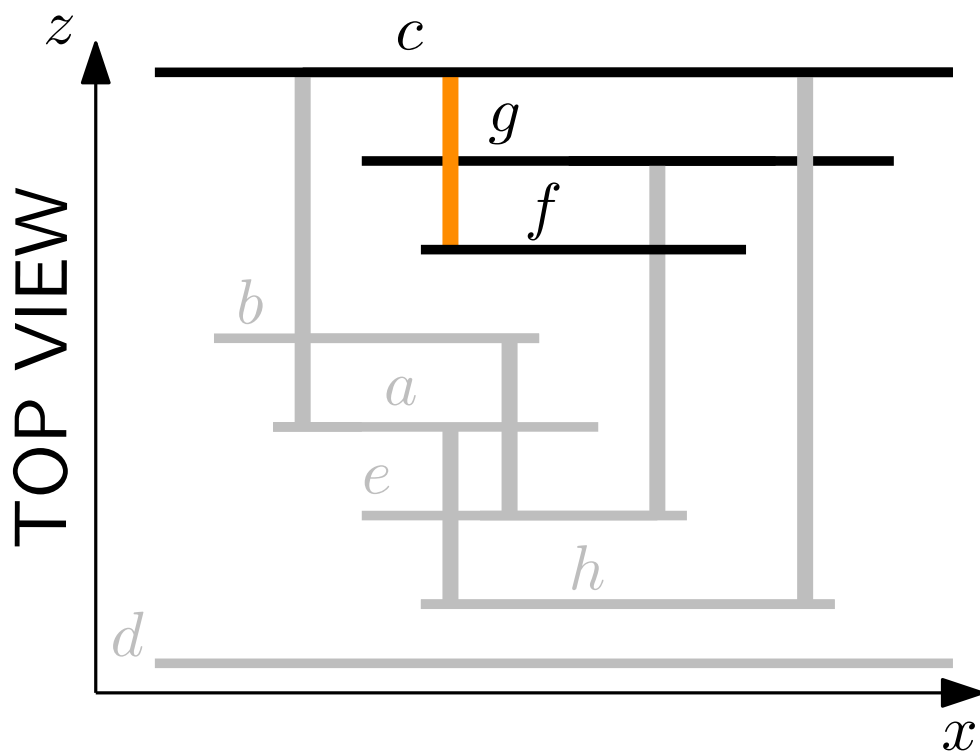
Idea: To realize the other visibilities we set the y -coordinates of the rectangles by using two orientations of (a subset of) the edges of P , called D_1 - for the top sides - and D_2 - for the bottom sides



Step 2: 1-visible ZPR

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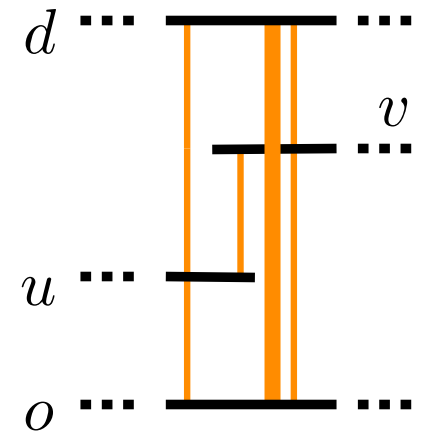
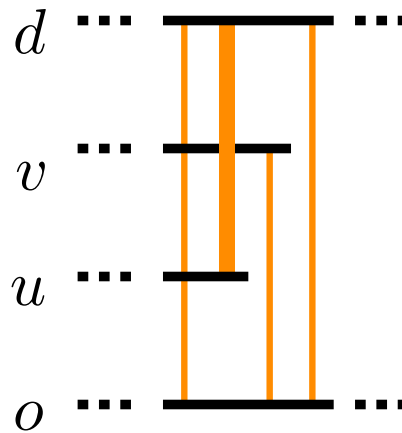
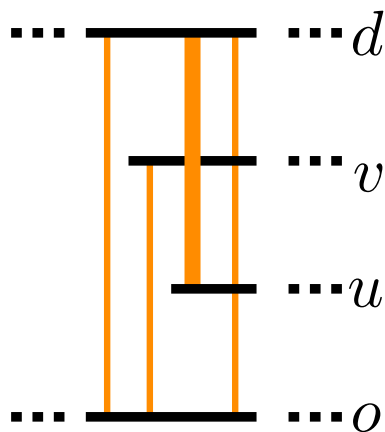
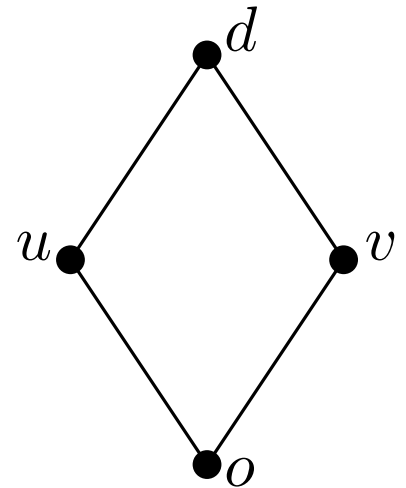
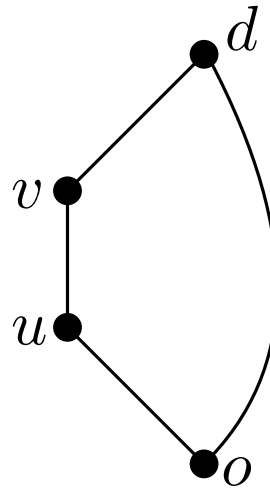
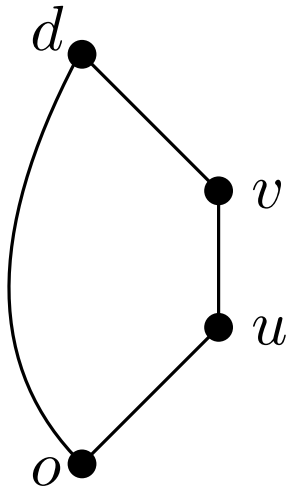
Idea: An edge oriented from u to v in D_1 (D_2) encodes that the top side (bottom side) of u will have y -coordinate greater (smaller) than the one of v



Step 2: 1-visible ZPR

Step 2: Transform the B1VR γ_1 into the ZPR γ

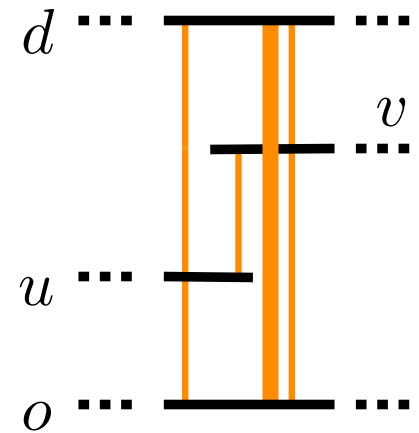
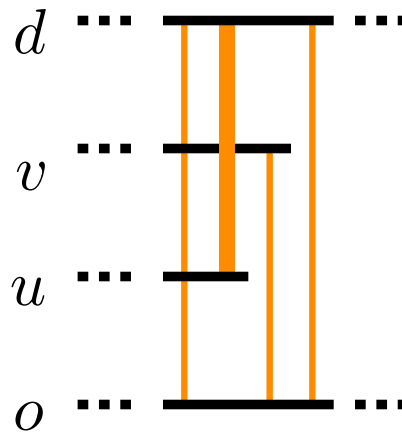
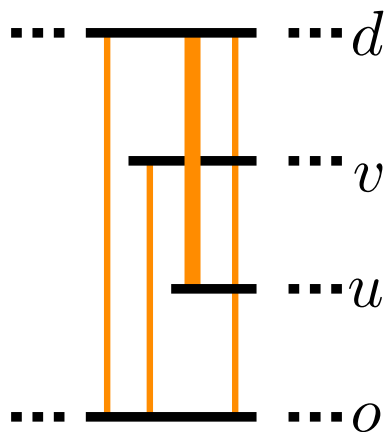
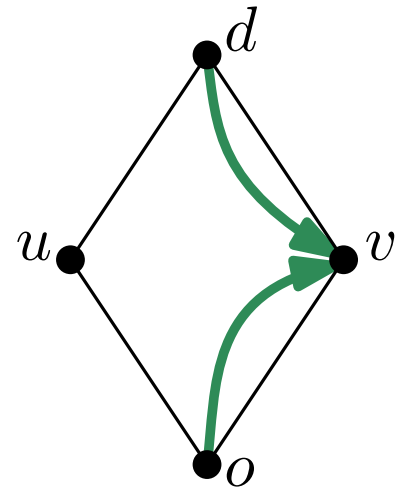
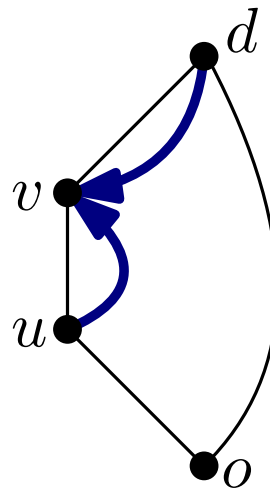
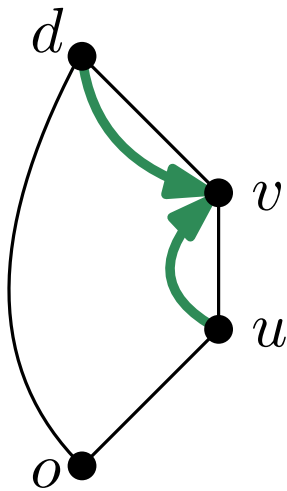
2a: Process the edges of each kite and apply a set of rules to obtain D_1 and D_2



Step 2: 1-visible ZPR

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To prove: No edge directed twice, and both D_1 and D_2 are acyclic

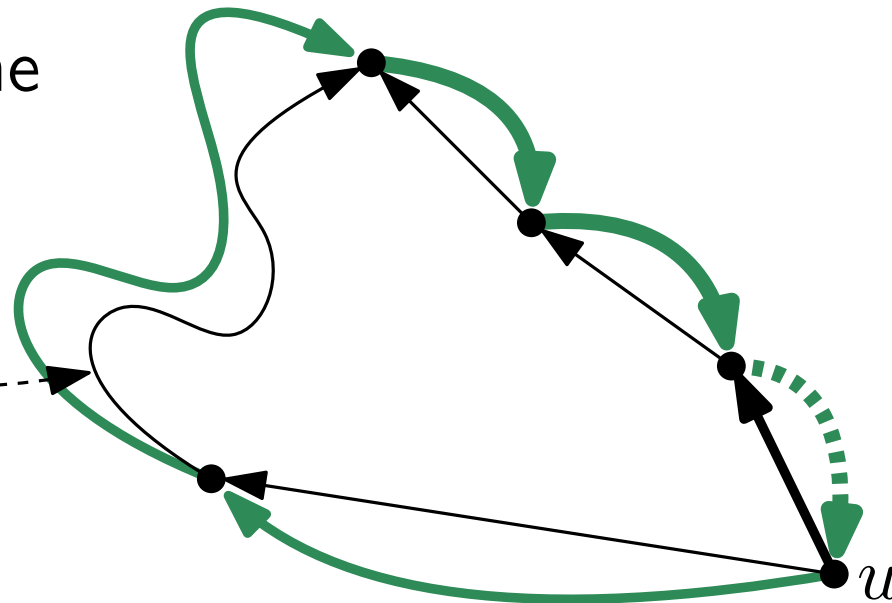
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To prove: No edge directed twice, and **both D_1 and D_2 are acyclic**

Assuming D_1 or D_2 has a cycle, one can contradict the rules used to construct D_1 or D_2 .

Black edges
oriented from the
bottommost to the
topmost endpoint
by looking at the
B1VR



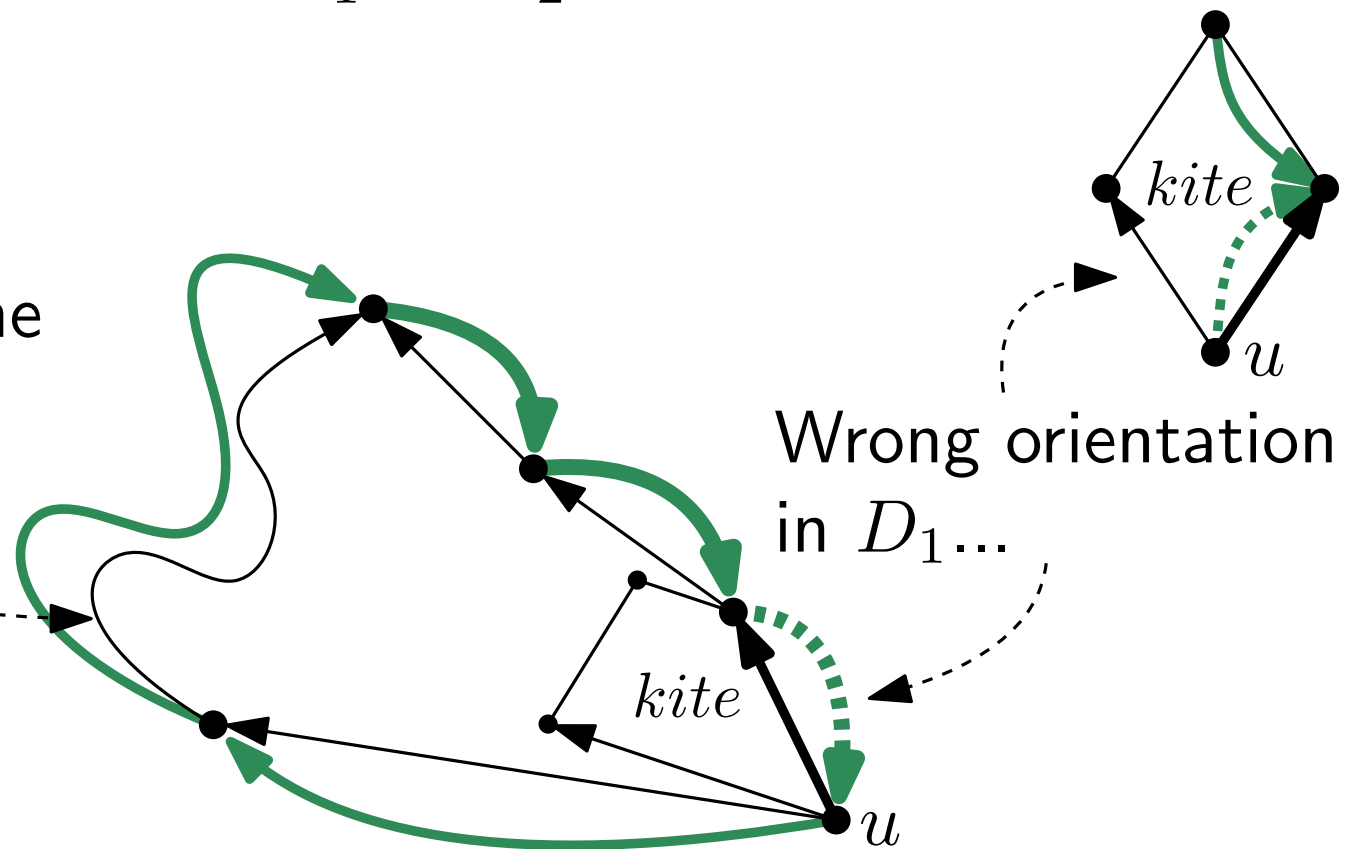
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Black edges oriented from the bottommost to the topmost endpoint in the B1VR



Step 2: 1-visible ZPR

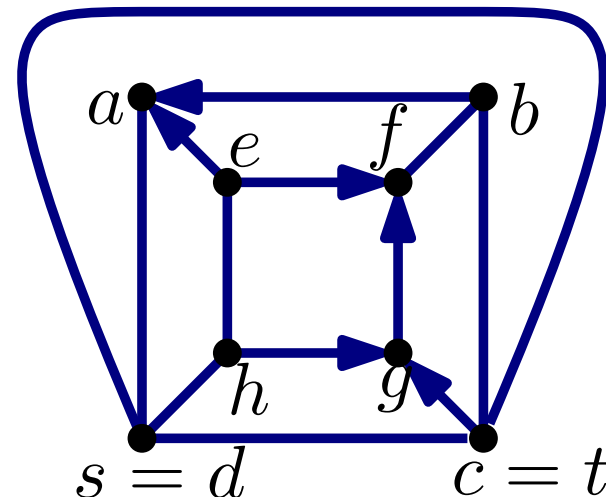
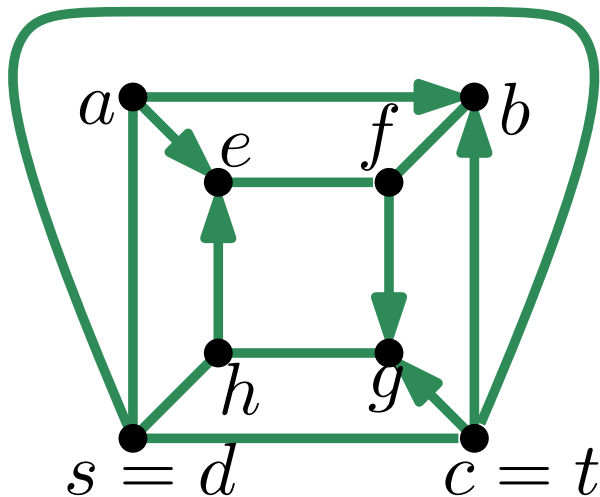
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2b. Compute a topological ordering of both D_1 and D_2 (each ordering might consists of several components).

This gives two total orderings (after possible concatenations) σ_1 and σ_2 of the vertices of G

$$\sigma_1 = \{c, a, h, f, b, e, g, d\}$$

$$\sigma_2 = \{h, c, g, e, b, f, a, d\}$$



Step 2: 1-visible ZPR

Step 2: Transform the B1VR γ_1 into the ZPR γ

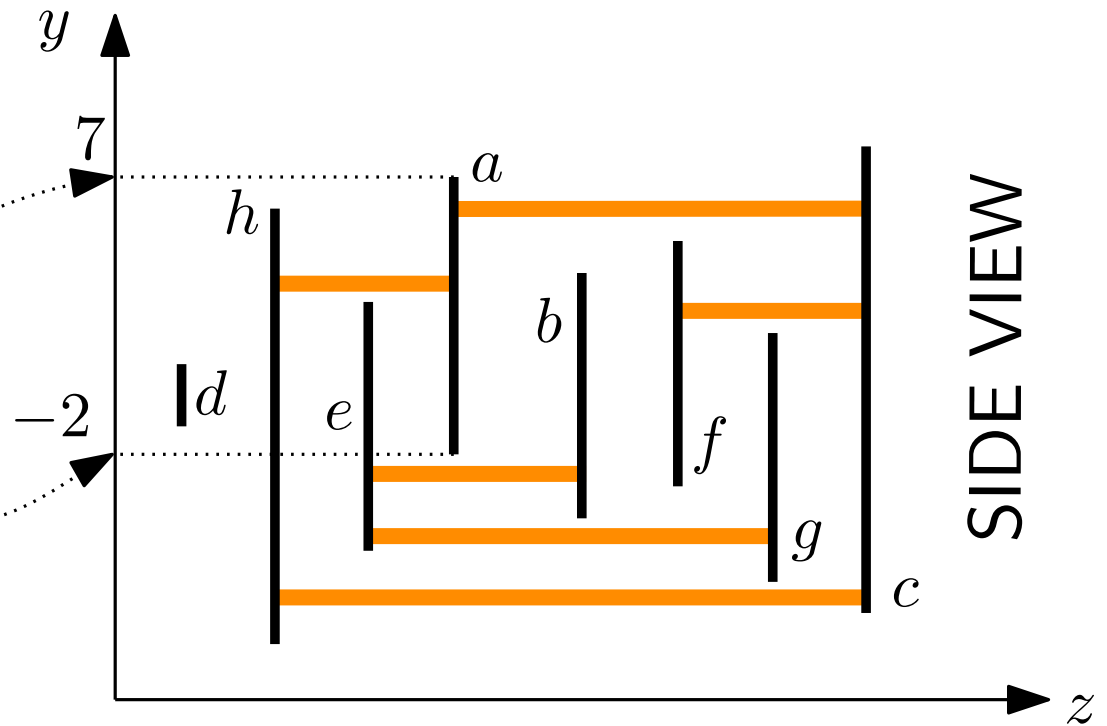
2c. Set the y -coordinate of the top side of the rectangle representing the i -th vertex in σ_1 equal to $n - i + 1$
Set the y -coordinate of the bottom side of the rectangle representing the i -th vertex in σ_2 equal to $i - n - 1$

$$\sigma_1 = \{c, a, h, f, b, e, g, d\}$$

$$\sigma_2 = \{h, c, g, e, b, f, a, d\}$$

$$top(\sigma_1(2) = a) = 7$$

$$bottom(\sigma_2(7) = a) = -2$$

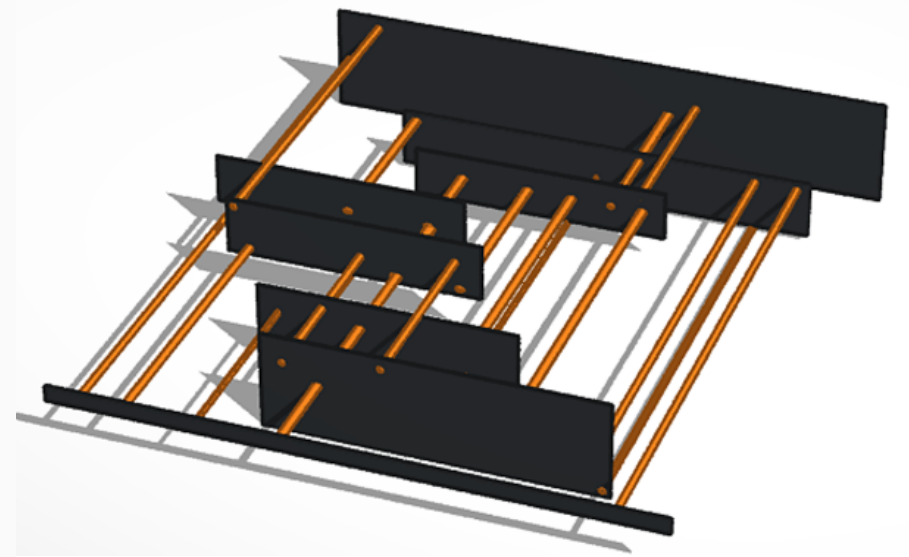
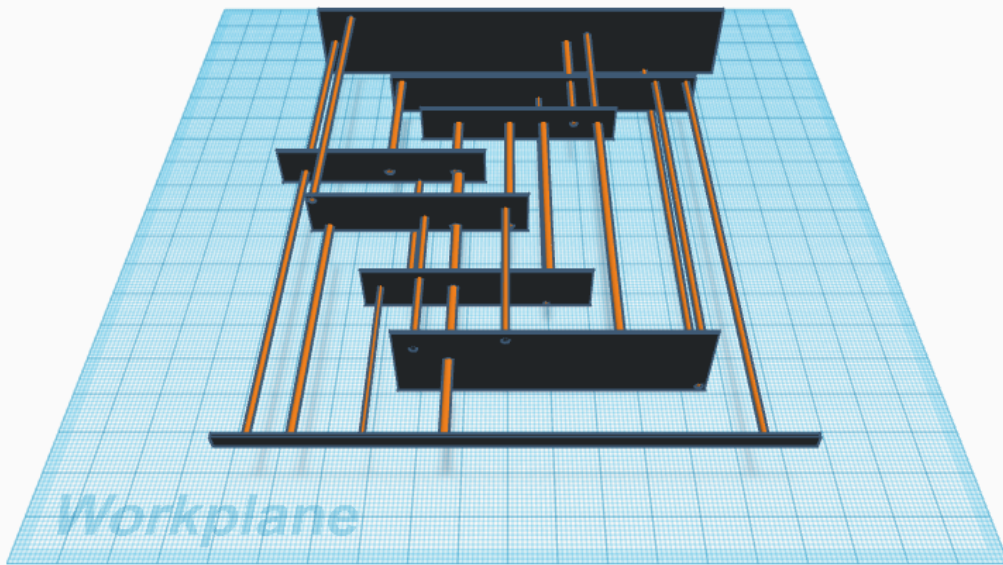


End!

Output: A 1-visible ZPR γ of G

Each step takes $O(n)$ time

The height of each rectangle is at most $2n$, hence γ takes $O(n) \times O(n) \times O(n)$ volume



Open problems

1. The algorithm by Brandenburg can be adjusted to compute B1VRs of optimal 2-planar graphs [Bekos et al. 2017]. Does every 2-planar graph admit a 1-visible ZPR?

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- 2.** Even more: can we generalize our result so to prove that every graph admitting a B1VR also admits a 1-visible ZPR?
- 3.** Does every 1-planar graph admit a 2.5D box visibility representation (i.e., vertices are axis-aligned boxes whose bottom faces lie on a same plane, and visibilities are both vertical and horizontal)?

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THANKS FOR YOUR ATTENTION!